

# Luke Bhan

[lbhan@ucsd.edu](mailto:lbhan@ucsd.edu) | [lukebhan.com](http://lukebhan.com) | [github](https://github.com) | [google scholar](https://scholar.google.com)

## EDUCATION

---

### University of California, San Diego (UCSD)

*Ph.D. Electrical and Computer Engineering*

La Jolla, CA

*Sept. 2022 - Present (Anticipated 2027)*

### Vanderbilt University

*M.S. Computer Science*

Nashville, TN

*August 2020 - May 2022*

### Vanderbilt University

*B.S. Computer Science, Physics, Applied Math (3 Majors)*

Nashville, TN

*August 2018 - May 2022*

## AWARDS, GRANTS, AND ACHIEVEMENT

---

### Department of Energy, Computational Science Graduate Fellowship (DOE CSGF)

- Full funding for 4 years of Ph.D. (500k+, 2022).

### Dean Underwood Memorial Award

- Awarded to the top graduating senior in Vanderbilt's Department of Physics and Astronomy.

### Best Student Paper Finalist (Learning for Dynamics and Control Conference 2025 - Top 3/119)

- For the paper titled [Neural Operators for Predictor Feedback Control of Nonlinear Delay Systems](#).

### Best Student Paper Award (Vanderbilt Department of Physics and Astronomy)

- For the paper titled [Signatures of atomic structure in subfemtosecond laser-driven electron dynamics in nanogaps](#).

## RESEARCH EXPERIENCE (FULL PUBLICATION LIST)

---

### Ph.D. UCSD | *Machine Learning, Robotics, and Intelligent Systems*

Sept. 2022 - Present

- Developed the first neural network model to achieve *resolution invariant* motion planning for 2D and 3D robotic systems via operator learning. Achieves approximately 50x speedup over numerical solvers and is discretization invariant enabling training on smaller grids with real-world employment on high resolution maps ([ICLR 2025](#)).
- Introduced neural networks (neural operators) for *provably* stable PDE control with applications to rocket propellant and chemical reactions ([TAC](#), [Automatica](#)). Enabled real-time implementation of a long-standing, but computational prohibitive control algorithm achieving 10<sup>3</sup>x speedup. Recognized in the [2023 CDC Bode Lecture](#) (top plenary lecture in control theory).

### B.S./M.S. Vanderbilt | *Computer Science and Physics*

August 2018 - May 2022

- *Computer Science*: Developed a series of reinforcement learning algorithms for fault-tolerant control (motor/battery damage) of UAVs and the Baxter robot ([ICRA 2018](#)).
- *Physics*: Designed a laser-driven quantum ratchet with applications to single nm sized transistors/processors ([Nano Letters](#)). Developed a new approach to *efficiently* simulate electrodynamic scattering using Fortran and an HPC cluster ([Phys Rev B](#), [Journal of Chemical Physics](#)).

## INTERN EXPERIENCE

---

### Amazon | *Applied Scientist Intern*

June 2025 - Sept 2025

- Fine-tuned and designed custom LLMs to provide adjustments for time-series forecasts predicting demands of over 30+ million Amazon products. Demonstrated that LLMs can effectively identify poor distributional forecasts which led to an internal Amazon Machine Learning Conference (AMLC) paper.

### Lawrence Berkeley National Lab | *Research Intern*

June 2024 - Sept 2024

- Developed randomized linear algebra (RandLA) solvers for distributed non-convex optimization (SQP) enabling real-time, parallel optimization (1x speedup per node) for control of dynamical systems.

### Mongo DB | *Software Engineering Intern*

June 2021 - August 2021

- Designed and coded (C++) the compression algorithm for MongoDB's [time-series database](#). Shrunk memory usage for users by 99%.

### T-Mobile | *Machine Learning Intern*

June 2020 - August 2020

- Created an internal analytics API that visualizes network loads to proactively identify and combat downtime.

## SKILLS

---

### Languages

Python, C++, Julia, Rust, L<sup>A</sup>T<sub>E</sub>X

### Frameworks

PyTorch, Hugging Face transformers, NumPy, Pandas, TensorFlow, Git

### Technical

ML (neural operators), robotics (ROS), optimization, PDEs, control theory, timeseries forecasting